

Official Open-Access Course @ University of Pisa, ContinuatAI, AIDA

Lecture 8: Frontiers in Continual Learning

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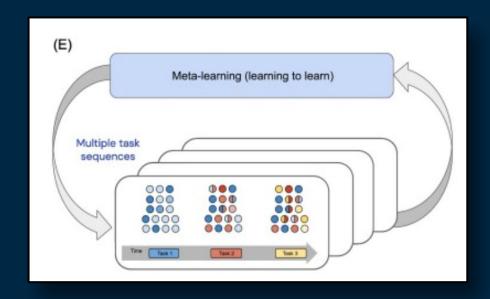
Continual Sequence Learning



Meta Learning & Continual Learning

Difference in Focus

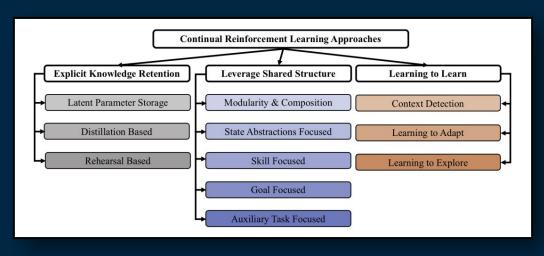
- Meta-Learning is about "learning to learn"
- Continual Learning is about learning reusable representations from non-stationary data
- Two main categories:
 - Meta Continual-Learning
 - Continual Meta-Learning



Continual Reinforcement Learning

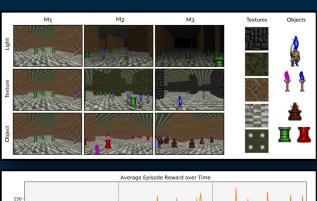
Difference in Focus

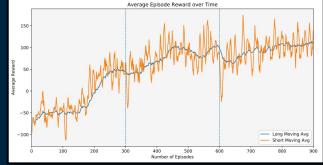
- Reinforcement Learning is about "learning from (sparse) rewards"
- Continual Learning is about learning reusable representations from non-stationary data
- Quite orthogonal objectives but some shared constraints (single agent view, non-stationary envs, sample bias, etc..)



Continual Reinforcement Learning in 3D Non-stationary Environments







Ideal Paradigm to Combine with CL

- No Continual Labeling
- Less Bias
- Why this is still not the case?
 - Changing the paradigm:
 More Data, Less
 Supervision
 - Less impactful applications (for now)

"Pure" Reinforcement Learning (cherry)

- The machine predicts a scalar reward given once in a while.
- A few bits for some samples

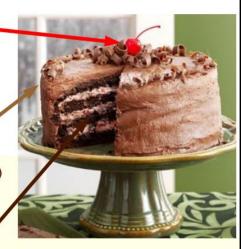
Supervised Learning (icing)

- The machine predicts a category or a few numbers for each input
- Predicting human-supplied data
- ▶ 10→10,000 bits per sample

Unsupervised/Predictive Learning (cake)

- The machine predicts any part of its input for any observed part.
- Predicts future frames in videos
- ▶ Millions of bits per sample
- (Yes, I know, this picture is slightly offensive to RL folks. But I'll make it up)

Y. LeCun, NeuIPS 2016

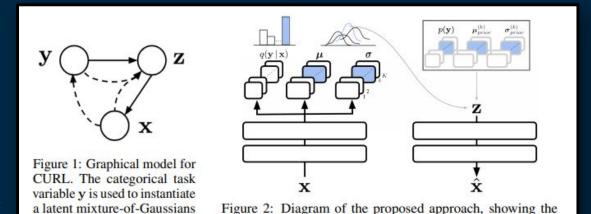


Continual Unsupervised Representation Learning

z, which is then decoded to x.

Key Ideas

- Fully Generative Approach
- y can be interpreted as representing some discrete clusters in the data
- Mixture of Gaussian with Dynamic Expansion
- Difficult to scale: tested only on MNIST and Omniglot

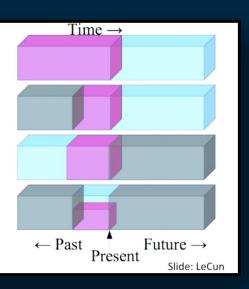


inference procedure and architectural components used.

Huge Exploration Opportunities

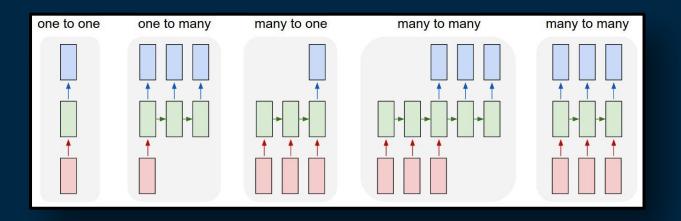
- Self-Supervised Learning
- Sequence Learning
- Contrastive Learning
- Hebbian-like Learning
- Active Learning
- Weakly/Semi-SupervisedLearning
- Randomized Networks

- Predict any part of the input from any other part.
- Predict the future from the past.
- ▶ Predict the future from the recent past.
- Predict the past from the present.
- Predict the top from the bottom.
- Predict the occluded from the visible
- Pretend there is a part of the input you don't know and predict that.



Huge Exploration Opportunities

- Self-Supervised Learning
- Sequence Learning
- Contrastive Learning
- Hebbian-like Learning
- Active Learning
- Weakly/Semi-Supervised
 Learning
- Randomized Networks



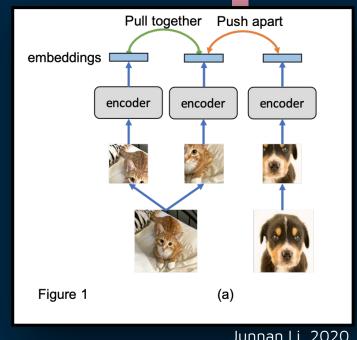
B. Ehret et Al. Continual learning in Recurrent Neural Networks. ICLR 2021.

Y. Cui et al. **Continuous online sequence learning with an unsupervised neural network model**. Neural Computation, 2016.

A. Cossu et Al. Continual Learning for Recurrent Neural Networks: an Empirical Evaluation. Elsevier Neural Networks, 2021.

Huge Exploration Opportunities

- Self-Supervised Learning
- Sequence Learning
- **Contrastive Learning**
- Hebbian-like Learning
- Active Learning
- Weakly/Semi-Supervised Learning
- Randomized Networks



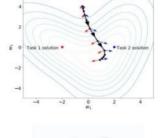
Junnan Li, 2020

Huge Exploration Opportunities

- Self-Supervised Learning
- Sequence Learning
- Contrastive Learning
- Hebbian-like Learning
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 Learning
- Randomized Networks

Gradient-based optimization and tug-of-war dynamics

- Continual Learning is a huge challenge for deep learning models because of gradient-based optimization.
- Gradient-based learning is effective and cheap, the de rigeur method for training neural networks for close to 4 decades.
- However, a close look at the learning dynamics reveals a problem.
- Each training sample produces a gradient for each parameter in the network that votes to make the parameter bigger or smaller.
- In a mini-batch, a gradient is produced by each sample in parallel and they are summed to decide the winning direction.
- The result is a tug-of-war over the direction of change of each parameter.





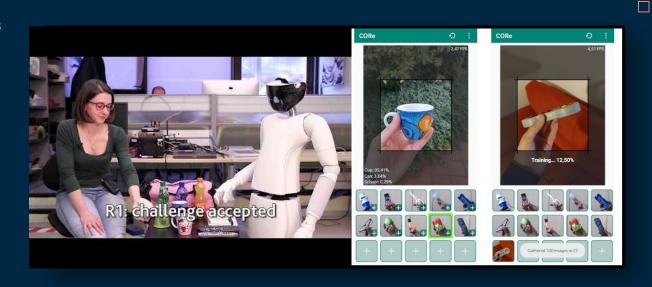


R. Pascanu, 202



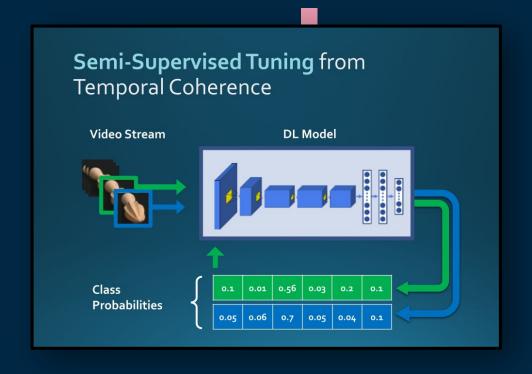
Huge Exploration Opportunities

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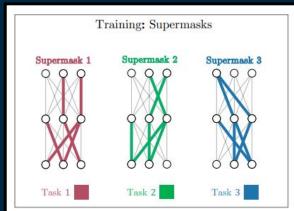
Huge Exploration Opportunities

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Huge Exploration Opportunities

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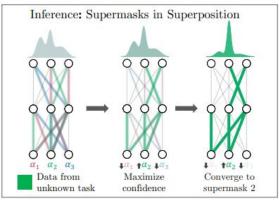


Figure 1: (**left**) During training SupSup learns a separate supermask (subnetwork) for each task. (**right**) At inference time, SupSup can infer task identity by superimposing all supermasks, each weighted by an α_i , and using gradients to maximize confidence.

M. Wortsman, 2020

Other relevant works in this area

- A. Bertugli et al. Few-Shot Unsupervised Continual Learning through Meta-Examples. Workshop on Meta-Learning at NeurIPS 2020.
- I. Muñoz-Martín et al. Unsupervised learning to overcome catastrophic forgetting in neural networks. IEEE Journal on Exploratory Solid-State Computational Devices and Circuits, 2019.
- L. Caccia et al. SPeCiaL: Self-Supervised Pretraining for Continual Learning, arXiv 2021.
- W. Sun et al. *ILCOC: An Incremental Learning Framework Based on Contrastive One-Class Classifiers.* CLVision Workshop at CVPR 2021.
- J. He et al. **Unsupervised Continual Learning Via Pseudo Labels.** arXiv 2020.
- S. Khar et al. Unsupervised Class-Incremental Learning through Confusion. arXiv 2021.



Sustainable AI Principles

General Principles

- Accuracy & Robustness
- Explainability, Transparency & Accountability
- Bias & Fairness
- Privacy & Security
- Human, Social and Environmental Wellbeing

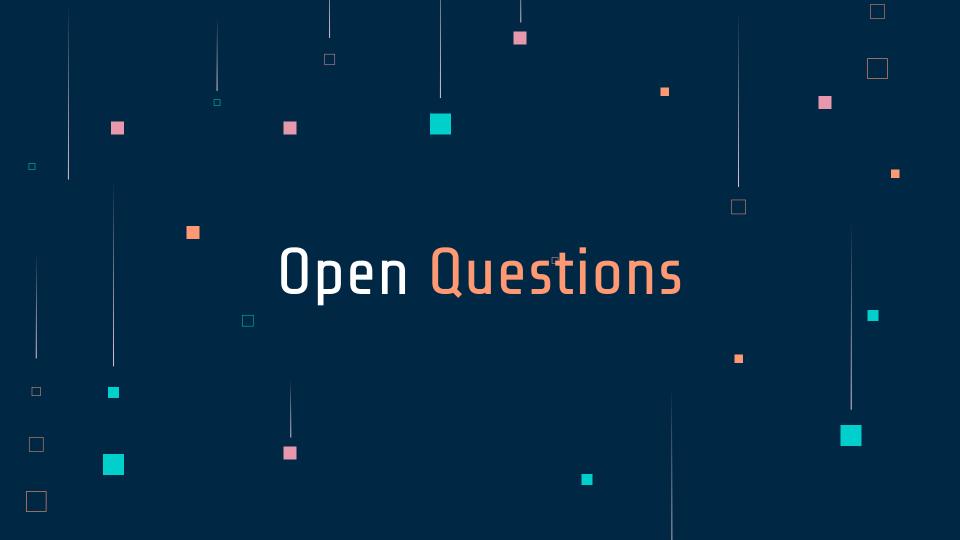
L. Royakkers et al. **Societal and ethical issues of digitization**. Ethics and Information Technology, 2018. B.D. Mittelstadt et al. **The ethics of algorithms: Mapping the debate**. Big Data & Society, 2016. A. Jobin et al. **The global landscape of AI ethics guidelines**. Nature Machine Intelligence, 2019. Cossu et al. **Sustainable Artificial Intelligence through Continual Learning**. CAIP 2021. https://www.aiforpeople.org/ethical-ai/

Continual Learning Impact

...On each Principle:

- Accuracy & Robustness → Robustness & Autonomy, Continual & Fast Improvement
- Bias & Fairness → CL as the new Agile: Bias & Fairness Patches
- Privacy & Security → Security Patches
- Human, Social and Environmental Wellbeing → improved efficiency & scalability: less energy consumption, CO2 emission; sustainable & "progressive" by design
- Explainability, Transparency & Accountability → Neuroscience-grounded, Human-centered AI

L. Royakkers et al. Societal and ethical issues of digitization. Ethics and Information Technology, 2018.
B.D. Mittelstadt et al. The ethics of algorithms: Mapping the debate. Big Data & Society, 2016.
A. Jobin et al. The global landscape of AI ethics guidelines. Nature Machine Intelligence, 2019.
Cossu et al. Sustainable Artificial Intelligence through Continual Learning.
CAIP 2021.
https://www.aiforpeople.org/ethical-ai/



Open Questions (1/2)

- 1. Is it possible to learn **robust**, **deep representations continually**?
- 2. Are currently addressed scenarios and eval metrics enough?
- 3. What is the right level of supervision?
- 4. How to know **what to forget** and **what to remember**?
- 5. What's the relationship with **concept drift**?
- 6. Is **replay** a research direction worth pursuing?
- 7. Is **computation** more important than **memory**?
- 8. Is **gradient descent** the right algorithm to learn continually?
- 9. Continual Meta-Learning & Meta-Continual Learning: what's the right relationship?
- 10. What is the relationship with **Sequence** and **Continual Learning**?

Open Questions (2/2)

- 1. Is **curiosity** important for continual learning?
- 2. What about **Curriculum Learning**?
- 3. **Compositionality** is a key aspect of human intelligence: what to expect for CL Systems?
- 4. **Self-Reflection***: accuracy of learned functions, given only unlabeled data?
- 5. **Self-reflection** that can detect every possible shortcoming (called impasse) of the agent*
- 6. (External) Knowledge and Reasoning*

...and much more!

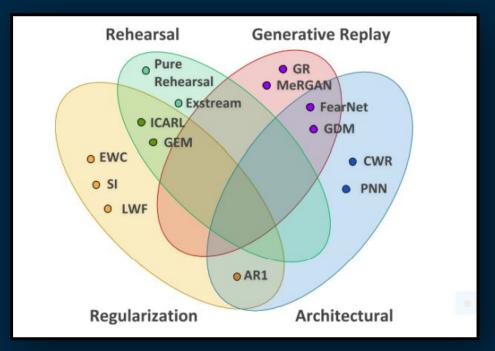
On the Future of CL (Short-Medium Term)

More Natural Scenarios

- **Domain**, **Task** and **Class-Incremental** are not enough.
- Longer streams of "experiences".
- More metrics, focus on scalability.

2. Move towards unsupervised training

- Mostly Semi-Supervised,
 Self-Supervised and Sequence
 Learning.
- 3. Hybrid Continual Learning Strategies
- 4. Continual Learning Applications



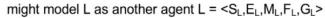
On the Future of CL (Long-Term)

- Fundamentally a question of agent architecture*
- 2. Two main paths for (deep) CL
 - a. Neuroscience-Inspired
 - b. Distributed Continual Learning

What should a theory of Learning Agents answer?

might model learning agent A as tuple <S,E,M,F,G,L>

- S = sensors
- E = effectors
- F = set of functions
- M = set of memory units
- G = graph specifying data flow among F, M, S, E
- L = learning mechanism

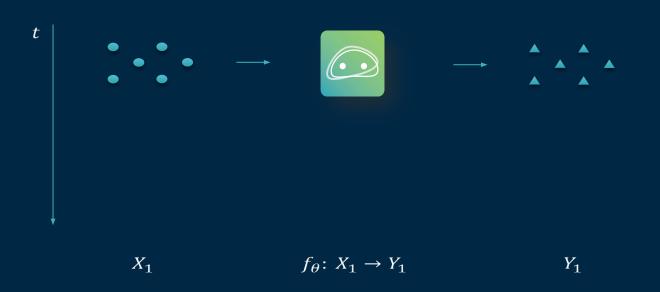


where S_L, E_L sense and act on Agent, especially its F, M, G

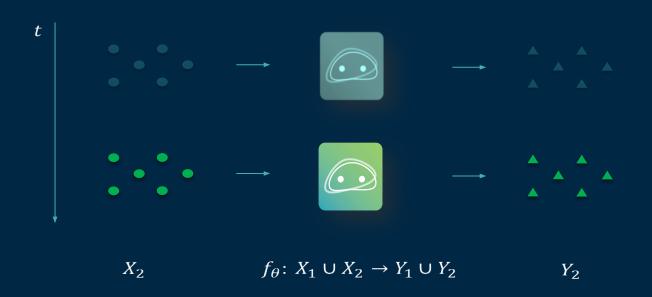




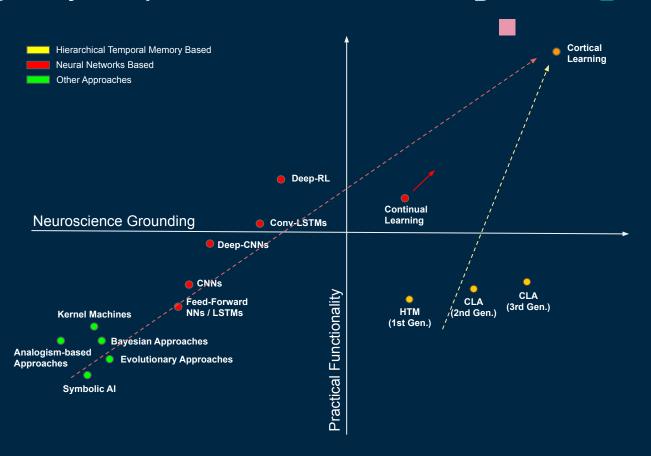
Continual Learning (CL)



Continual Learning (CL)



Biologically-Inspired Continual Learning



Agent-Centric Learning

A Continual Learning algorithm trains a single agent

Example: a robot that learns to grasp different objects over time.

Desiderata

- Replay-free CL
- Limited computational resources
- Task-free CL
- Online CL



A Fork in the CL Road



Distributed Continual Learning

A Continual Learning algorithm trains a **single agent** (as before).

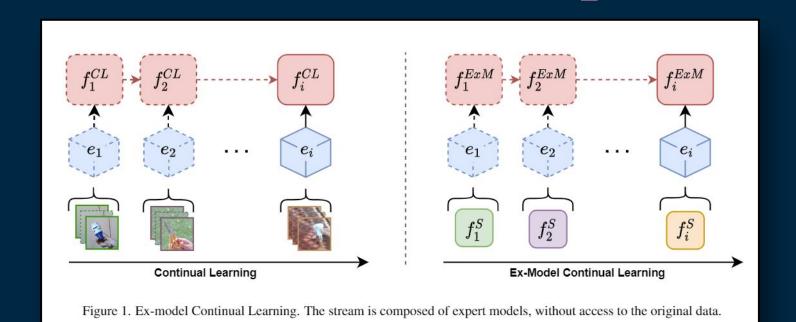
Example: a fleet of independent robots that learn to grasp different objects over time.

Desiderata

- Reuse of expert knowledge
- Efficient and distributed learning
- **Independent agents** (unlike federated learning)
- Privacy (at will)



Ex-Model Continual Learning (ExML)



Ex-Model: Continual Learning from a Stream of Pre-Trained Models. A. Carta, A. Cossu, V. Lomonaco, D. Bacciu. 2021.

Issues and Missed Opportunities

- Expert models: continual learning should reuse knowledge from expert agents (i.e. the model's parameters), such as local personalized models or large pretrained models
- **Distributed learning**: agents in a distributed environment should be able to learn independently and to share knowledge efficiently at the same time (sharing the models).
- Sample efficiency: learning from raw data may be in-efficient due to noise and redundancy inherent to high-dimensional perceptual data.
- **Privacy**: sharing knowledge between agents must be limited by privacy constraints, and each agent should be allowed to set its privacy constraints.

Ex-Model Continual Learning (ExML)

- The Continual Learning model never gets access to the original data, only the expert's model.
- We cannot maintain all the experts in memory.
- We are allowed to maintain a memory of generated / out-of-distribution examples.
- This approach open the doors to the efficient on-demand integrations of "neural skills".
- **Privacy by design**: we never share private data which can stay on the source device.

ExML Scenario The objective of the ExML scenario is to continuously update a model f_i^{ExM} whenever a new expert f_i^S becomes available. Notice that the loss $\mathcal{L}_{exp}(f_i^{ExM}, \mathcal{D}^i_{train})$ cannot be evaluated since we do not have access to the original data. Since the stream of models may be unbounded, training strategies must be scalable up to a large number of experts. Therefore, ex-model algorithms cannot keep in memory all the previous experts. As a result, there are two constraints in an ExML scenario: lack of access to the original data and limited computational resources.

Overall, an ExML algorithm \mathcal{A}^{ExM} is a function with the following signature:

$$\mathcal{A}^{ExM}: \langle f_{i-1}^{ExM}, f_i^S, \mathcal{M}_{i-1}^{ex}, t_i \rangle \to \langle f_i^{ExM}, \mathcal{M}_i^{ex} \rangle,$$
 (4)

where f_i^{ExM} is the current model, f_i^S the current expert from the stream, \mathcal{M}_{i-1}^{ex} is a set of samples from out-of-distribution data or synthetically generated and currently available to the model (Section 4), and t_i the task label information. Again, notice that task labels are optional and they may not be available in many scenarios. The objective of ex-model algorithms is to minimize Eq. 2, the loss over the original (and unavailable) data stream.

Ex-Model Distillation

- Data-free Distillation as an elegant way to merge two pre-trained models
- We assume no access to the original data as we should stay agnostic w.r.t. to the experts training constraints
 - Synthetic data generation via optimization or auxiliary data
- Each expert's model can be trained separately, completely agnostic w.r.t. the continual learning scenario

Algorithm 1 Ex-Model Distillation

Require: Stream of pretrained experts S and a continually learned model f^{ExM} .

```
1: \mathcal{M}_0^{ex} \leftarrow \{\}

    bempty buffer
    bem
       2: for f_i^S in S do
       3: \mathcal{D}_i^{ex} \leftarrow \mathcal{A}^{gen}(f_i^S, \frac{N}{\epsilon})
                                              \tilde{\mathcal{M}}_{i-1}^{ex} \leftarrow subsample(\mathcal{M}_{i-1}^{ex})
                                               \mathcal{M}_{i}^{ex} \leftarrow \tilde{\mathcal{M}}_{i-1}^{ex} \cup \mathcal{D}_{i}^{ex}
                                                      for k in 1, \ldots, n_{iter} do \triangleright Knowledge Distillation
                                                                                          \langle x^k, y^k \rangle \leftarrow sample(\mathcal{M}_i^{ex})
                                                                                    y^{curr} \leftarrow f^{ExM}(x^k)
                                                                                     \tilde{y} \leftarrow get\_target(x^k)
                                                                                                                                                                                                                                                                                                                                                                                                                      ⊳ Eq. 8
                                                                                     L \leftarrow \mathcal{L}_{ED}(y^k, \tilde{y}^k, y^k)
                                                                                         do SGD step on L
  11:
                                                            end for
  12:
13: end for
```

Some Preliminary Results

Table 2. Stream accuracy computed on the test set for MNIST and CIFAR10 continual learning scenarios. Ensemble methods' results are not shown for joint scenarios because ensembling is not necessary when there is a single model.

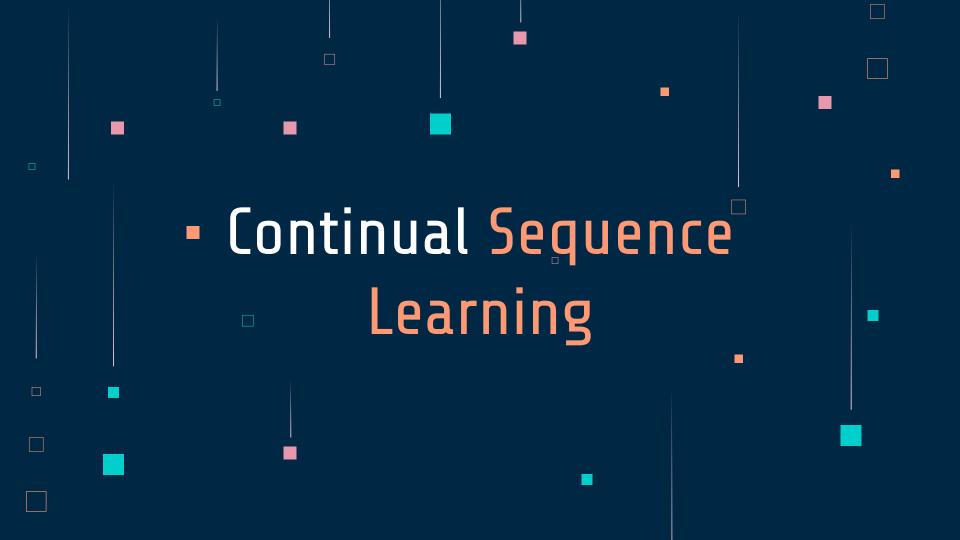
	Ex-model scenario	MNIST		CIFAR10		
		Joint	NC	Joint	NC	MT
Oracle	Х	93.71 ± 0.28	99.42 ± 0.19	87.37±1.11	96.58 ± 0.86	96.58 ± 0.86
Ensemble Avg.	×	-	$33.40{\pm}4.74$	_	51.85 ± 2.37	-
Min Entropy	X	5 - 5	$39.41{\scriptstyle\pm5.27}$	-	52.03 ± 2.67	_
Param. Avg.	1	8==0	20.11±0.97	1 - 1	10.00±0.00	51.85 ± 2.37
Model Inversion ED	/	93.09 ± 1.43	43.23 ± 3.00	$64.55{\pm}3.25$	17.40 ± 3.96	61.71 ± 7.52
Data Impression ED	/	92.12 ± 0.88	36.05 ± 6.74	52.64 ± 5.82	24.70 ± 6.85	61.15 ± 3.92
Aux. Data ED	/	89.35 ± 0.18	35.48 ± 6.35	76.94 ± 2.68	41.35 ± 5.83	60.72 ± 3.70

Challenges

- Model distillation is quite a complex task without the original data
- Generating training samples without the original data is very challenging (especially in terms of quality and diversity)
- What about efficiency? Data-free knowledge distillation can be computationally intensive.
- Some efficient selective pruning + ensembling methods may be interesting to study
- More specific distributed scenarios may allow a simplification of the problem's constraints. For
 example, a shares training protocol for the experts, or access to a pretrained generator, which may
 significantly reduce the overall problem complexity

Opportunities

- Federated Learning requires frequent sync (large bandwidth) and a shared single stakeholder training protocol
- Federated learning assumes homogeneity in the model architecture
- Federated Learning is not designed to handle non-stationarity
- Federated Learning can be seen a **constrained version of Ex-Model Continual Learning**, where the learning agents are controlled by a centralized protocol and synchronized frequently.
- ExML: opening the path for a Marketplace of Neural Skills for Al systems
- ExML: a new exciting path for Distributed Continual Learning machines!







Continual Sequence Learning

learning from a dynamic stream of temporally-correlated patterns



Andrea Cossu – Continual Learning course @ Unipi

PhD student @ SNS, Unipi PAI Lab, ContinualAI, CIML https://andreacossu.github.io/ andrea.cossu@sns.it



TL;DR



- Temporal correlation is a powerful source of information with many applications
- Continual Sequence Learning opens to new CL scenarios
- Applying CL strategies in recurrent models is not as straightforward as one may think
- NLP is currently the driving field for Continual Sequence Learning



Why should I care?



• Sequential data processing tasks are widespread

Stock prediction

Urban mobility

Natural Language Processing

Robot control

Video Processing

Human Activity Recognition



Sequences: challenges and opportunities



Temporal correlation is a (powerful) source of information!

- What is important and what can be discarded?
- What do you expect to receive next?
 - Can you lower the amount of supervision?
- Replay!

Temporal correlation introduces new challenges

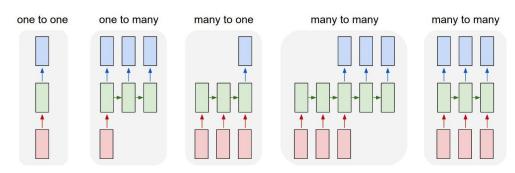
- Long/Short-term memory
- Computational **efficiency** (e.g. RNNs)



Scenarios for Continual Sequence Learning



- X-incrementals are still there
- Online / streaming continual sequence learning
 - next-item prediction (unsupervised!)
 - item-to-item prediction (classification/regression at each timestep)
 - We will see another example in the following (NLP)

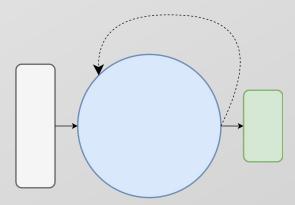




A brief tour of CL with RNNs



- Few contributions available
- RNNs ad-hoc models for temporal correlations
- Architectural strategies, regularization strategies, ...



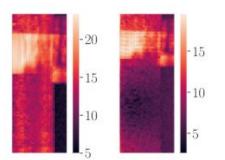


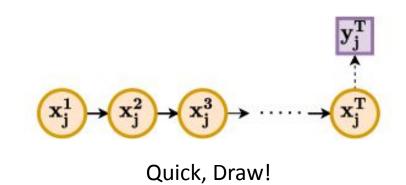
Benchmarks for Continual Sequence Learning



• Sequence classification tasks

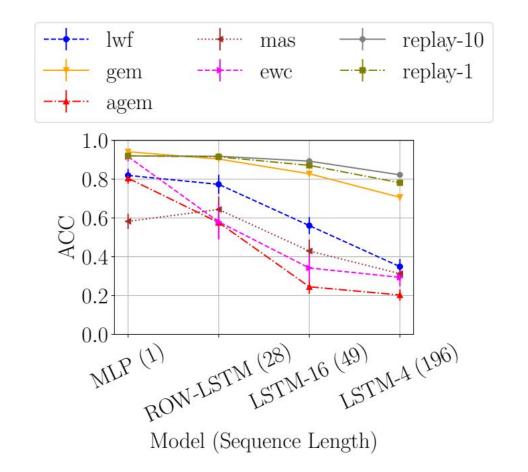
Split / Permuted MNIST pixel-wise
 Synthetic Speech Commands







Continual learning for recurrent neural networks: An empirical evaluation, A. Cossu, A. Carta, V. Lomonaco, D. Bacciu, *Neural Networks*, 2021.







Sequence Length effect on forgetting

Continual learning for recurrent neural networks: An empirical evaluation,

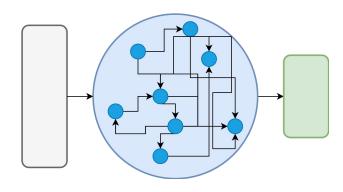
A. Cossu, A. Carta, V. Lomonaco, D. Bacciu, Neural Networks, 2021.



Echo State Networks and CL



- Untrained recurrent connections
 - you cannot forget, if you are not changing
- Treat reservoir as pretrained model
- Apply CL strategies only on the trained output layer
 - which is often linear
 - allows for the design of simple and efficient strategies
 - Deep Streaming LDA
- Neuromorphic deployment







Trends of NLP in CL

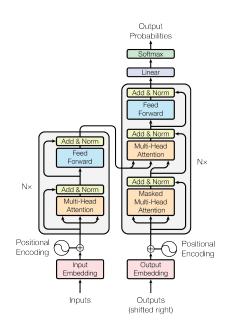


Keep your knowledge updated



NLP is driving the Continual Sequence Learning topic

- Transformers: standard de-facto in NLP
- Promising scenario: Dynamic Language Modelling
 - Language models can be used to solve many downstream tasks
 - Keep your language model updated
 - Temporal generalization, adapting to new information

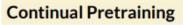


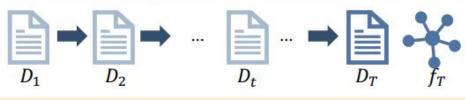
Attention is All you Need, A. Vaswani et al, NeurlPS, 2017.



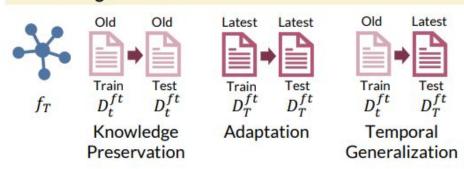
A Continual Sequence Learning scenario for NLP

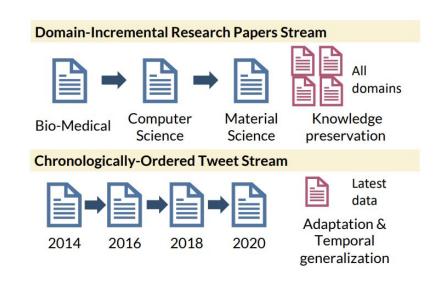






Fine-Tuning & Evaluation







The future ahead

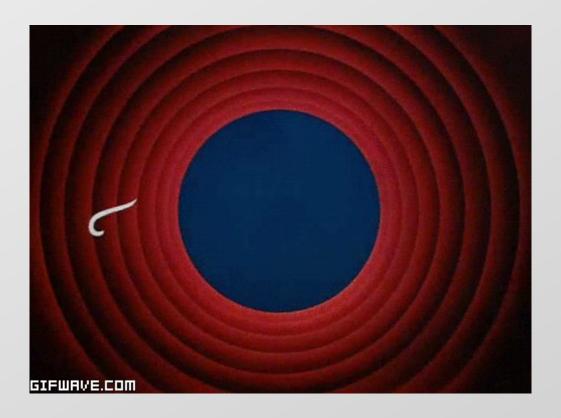


- Move away from traditional CL scenarios
- Understand how to exploit temporal correlation
- Adapt CL objectives we can forget, can't we?
- Real-world applications are out there, waiting

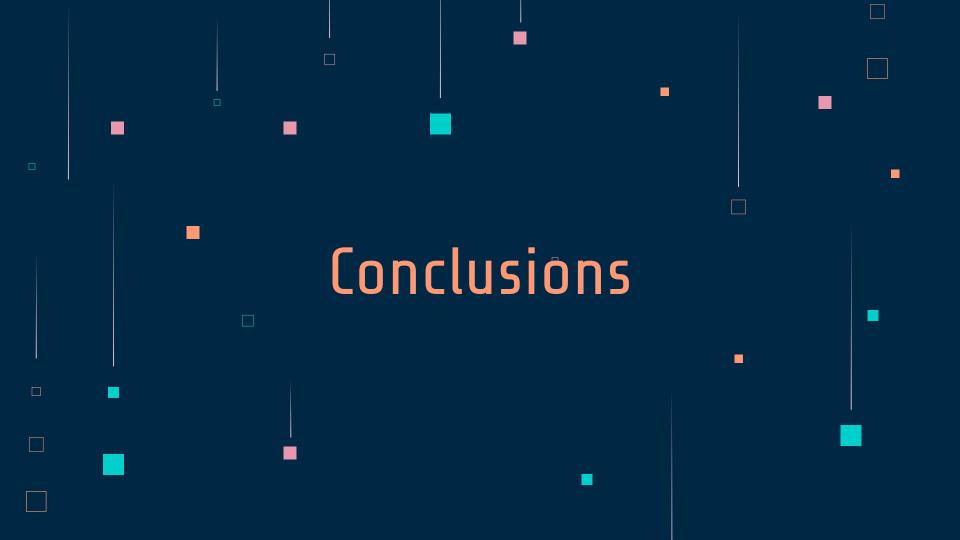








https://andreacossu.github.io/ andrea.cossu@sns.it



Conclusions

What we have seen

- Significant and growing Interest in the last few years on Continual learning within Deep Learning
- Significant improvements over standard benchmark but focus still mostly on simplified scenarios and forgetting centered metrics
- Huge space of possible and significant explorations

Take-Home Messages

- Continual Learning is a paradigm-changing approach trying to break the fundamental i.i.d. assumption in statistical learning
- CL pushes for the next step in Neuroscience-grounded approaches to learning
- 3. CL pushes for the next generation of truly intelligent robust and autonomous Al systems: **efficient**, **effective**, **scalable**, **hence sustainable**





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THANKS





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